

UNIT-I:POWER SYSTEM

Transmission line parameters; Representation of short, medium, and long transmission lines – ABCD parameters; Circle Diagram; Per Unit representation; 3- Φ system; Short Circuit Studies; Sequence Networks; Load-flow Studies – Gauss Seidel method, Newton- Raphson Method; Automatic Generation Control; Load-Frequency Control; Automatic Voltage Regulator; Power System Stability – Equal area criteria; Swing Equation; Optimal Load dispatch in Power System. Protection Schemes for Transformer, Generators and Transmission Lines.

UNIT -II:POWER ELECTRONICS AND DRIVES

Characteristics and ratings of different thyristor family devices, their turn on and turn off methods with their protection, series and parallel connection of SCRs and their derating, controlled single phase and three phase rectifiers for different types of load viz. R, R-L, R-L-E, single phase and three phase voltage source and current source inverter, cycloconverter, choppers, PWM techniques, Characteristics and principle of AC and DC machines, Methods of conventional controls and application of static controls and microprocessor based controls for AC and DC machines.

UNIT -III:COMPUTER TECHNOLOGY

Soft Computing (Basics of neural network, fuzzy logic, genetic algorithm, wavelets). Digital Electronics: Adder/Subtractor, Multiplexer/Demultiplexer, Serial and parallel operations; Computer and its Applications: Fundamentals of Computer Architecture (representation of information, control unit, bus organisation, memory, I/O devices), Introduction to data Structures (arrays, linked list, graphs, queue, stacks), Object Oriented programming (classes and objects, inheritance, polymorphism), Fundamentals of Operating Systems (Operating System Structure, management of resources),

UNIT:-IV:CONTROL AND INSTRUMENTATION

Mathematical Modeling of physical systems, Transfer function of linear systems, Steady state errors and error constants, static error coefficients Time domain analysis, Stability of control system, Routh-Hurwitz's stability criterion. Root locus plots, analysis of control system by root loci. Relationship between time and frequency response, Polar plot, Bode's Plot, Nyquist plot and Nyquist stability criterion, Relative Stability, Phase and Gain Margins, Constant M and N circle. Design of Feedback Controllers: Design of Proportional, Integral, Derivative, PI, PID controllers of first, second order systems. Control loop with auxiliary feedback, Feed forward control, Practical Controller tuning tips, Ziegler-Nichols' tuning methods. Compensation design using Bode Diagram and Root Locus technique, Reshaping the Root Locus, Cascade Lag, Lead and Lag-Lead compensators. State Variable concepts, State model, State transition matrix, conversion of state-variable modes to transfer functions, conversion of transfer function to canonical state-variable models, solution of state equation, concepts of controllability and observability. Stability Improvement by state feedback, Necessary and sufficient conditions for arbitrary pole placement, State regulator theory, design of state observer, Servo design: Introduction of reference input by feed forward control. Recent advances in control system design technologies.

Classification of Instruments, Moving iron, Moving Coil, Permanent magnet, and Dynamometer types. Thermal, Electrostatic Rectifier Instruments, transformers, CT, PT, Power measuring instruments, power factor, frequency meters and synchroscope. Measurement of flow, medium and high resistances AC and DC measuring bridges, Magnetic measurement. General Transducers voltage, current, phase angle, optical, Hall effect and Industrial transducers Electronic voltmeters, Vacuum Tube Voltmeter (VTVM), data acquisition system, spectrum analyses, sensors Measuring or sensing devices in different application, Generalized performance characteristics of the measuring instruments. Physical and chemical sensors, Principle of working of physical and chemical sensors, interface electronics circuits for instruments/sensor for data manipulation,

transmission and recording Computer aided measurement of voltage current power energy frequency phase angle. High voltage measurement.

UNIT -V:ELECTRONICS AND COMMUNICATION

Biasing and bias stability of transistor and FET amplifiers. Amplifiers: single and multi stage, differential and operational, feedback, and power. Frequency response of amplifiers. Simple op-amp circuits. Filters. Function generators and wave-shaping circuits, 555 Timers. Power supplies. Logic gates; digital IC families (DTL, TTL, ECL, MOS, CMOS). Combinatorial circuits: arithmetic circuits, code converters, multiplexers, decoders, PROMs and PLAs. Sequential circuits: latches and flip-flops, counters and shift registers. Sample and hold circuits, ADCs, DACs. Operational Amplifiers and other analog ICs., Semiconductor memories. Microprocessor (8085): architecture, programming and I/O interfacing.

Amplitude and angle modulation and demodulation systems, spectral analysis of these operations, superheterodyne receivers. Signal-to-noise ratio (SNR) calculations for amplitude modulation (AM) and frequency modulation (FM) for low noise conditions. Fundamentals of information theory and channel capacity theorem. Digital communication systems: pulse code modulation (PCM), differential pulse code modulation (DPCM), digital modulation schemes: amplitude, phase and frequency shift keying schemes (ASK, PSK, FSK), matched filter receivers, bandwidth consideration and probability of error calculations for these schemes. Basics of TDMA, FDMA and CDMA and GSM.